

Lower bounds

So far we have seen positive results: basic algorithmic techniques for fixed-parameter tractability.

What kind of negative results we have?

- Can we show that a problem (e.g., **CLIQUE**) is **not** FPT?
- Can we show that a problem (e.g., **VERTEX COVER**) has **no** algorithm with running time, say, $2^{o(k)} \cdot n^{O(1)}$?

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This would require showing that $P \neq NP$: if $P = NP$, then, e.g., k -**CLIQUE** is polynomial-time solvable, hence FPT.

Can we give some evidence for negative results?

Classical complexity — reminder

NP:

- The class of all languages that can be recognized by a polynomial-time NTM.
- The class of all languages with a witness of polynomial size

Nondeterministic Turing Machine (NTM): single tape, finite alphabet, finite state, head can move left/right only one cell. In each step, the machine can branch into an arbitrary number of directions. Run is successful if at least one branch is successful.

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Polynomial-time reduction from problem P to problem Q : a function ϕ with the following properties:

- $\phi(x)$ is a yes-instance of $Q \iff x$ is a yes-instance of P ,
- $\phi(x)$ can be computed in time $|x|^{O(1)}$.

Definition: Problem Q is **NP-hard** if any problem in **NP** can be reduced to Q .

If an **NP-hard** problem can be solved in polynomial time, then every problem in **NP** can be solved in polynomial time (i.e., $P = NP$).

Parameterized complexity

To build a complexity theory for parameterized problems, we need two concepts:

- An appropriate notion of reduction.
- An appropriate hypothesis.

Polynomial-time reductions are not good for our purposes.

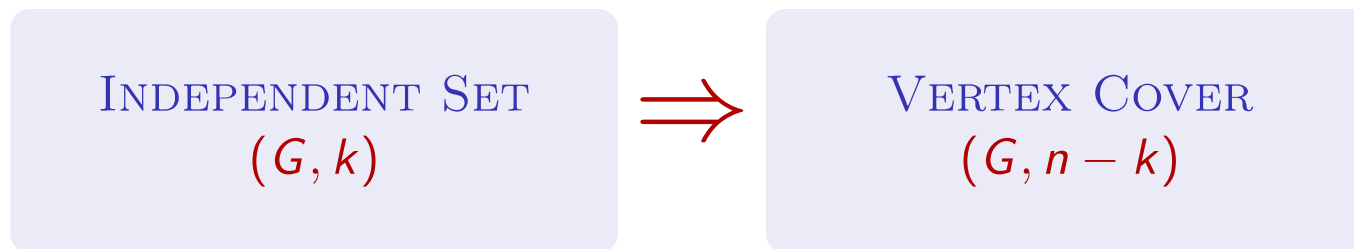
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Fact: Graph G has an independent set $k \Leftrightarrow G$ has a vertex cover of size $n - k$.



- This is a correct polynomial-time reduction.
- However, VERTEX COVER is FPT, but INDEPENDENT SET is not known to be FPT.

Parameterized reductions

Definition

Parameterized reduction from problem A to problem B : a function ϕ with the following properties:

- $\phi(x)$ is a yes-instance of $B \iff x$ is a yes-instance of A ,
- $\phi(x)$ can be computed in time $f(k) \cdot |x|^{O(1)}$, where k is the parameter of x ,
- If k is the parameter of x and k' is the parameter of $\phi(x)$, then $k' \leq g(k)$ for some function g .

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Theorem

If there is a parameterized reduction from problem A to problem B and B is FPT, then A is also FPT.

Intuitively: Reduction $A \rightarrow B$ + algorithm for B gives an algorithm for A .

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Non-example: Transforming an INDEPENDENT SET instance (G, k) into a VERTEX COVER instance $(G, n - k)$ is **not** a parameterized reduction.

Example: Transforming an INDEPENDENT SET instance (G, k) into a CLIQUE instance (\overline{G}, k) is a parameterized reduction.

Parameterized reductions

Theorem

If there is a parameterized reduction from problem A to problem B and B is FPT, then A is also FPT.

Proof: Suppose that

- the reduction has running time $f(k)n^{c_1}$,
- the reduction creates an instance with parameter at most $g(k)$, and
- B can be solved in time $h(k)n^{c_2}$.

Then running the reduction and solving the created instance of B gives an algorithm for A with running time

$$f(k)n^{c_1} + h(g(k)) \cdot (f(k)n^{c_1})^{c_2} \leq f'(k)n^{c_1 c_2}$$

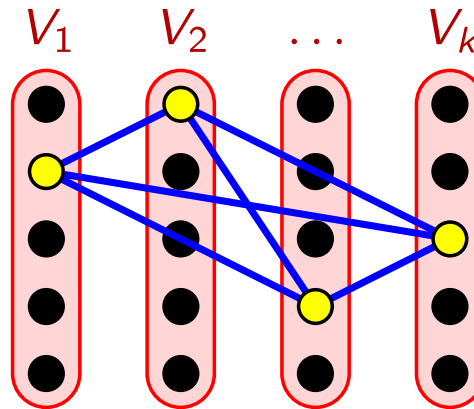
for some function f' .

MULTICOLORED CLIQUE

A useful variant of **CLIQUE**:

MULTICOLORED CLIQUE: The vertices of the input graph G are colored with k colors and we have to find a clique containing one vertex from each color.

(or **PARTITIONED CLIQUE**)



Theorem

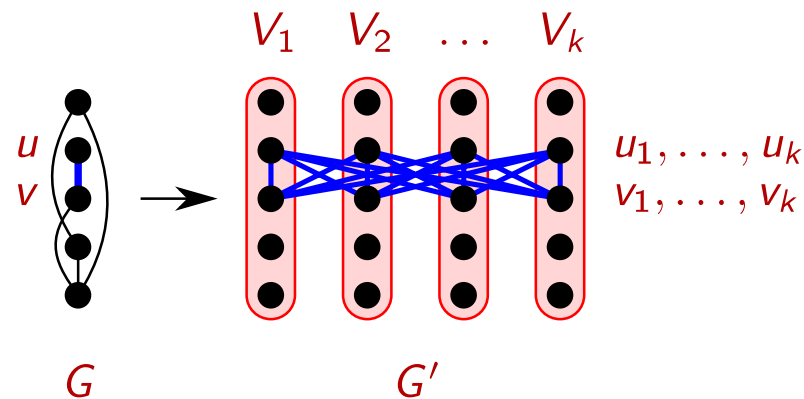
There is a parameterized reduction from **CLIQUE** to **MULTICOLORED CLIQUE**.

MULTICOLORED CLIQUE

Theorem

There is a parameterized reduction from **CLIQUE** to **MULTICOLORED CLIQUE**.

Create G' by replacing each vertex v with k vertices, one in each color class. If u and v are adjacent in the original graph, connect all copies of u with all copies of v .



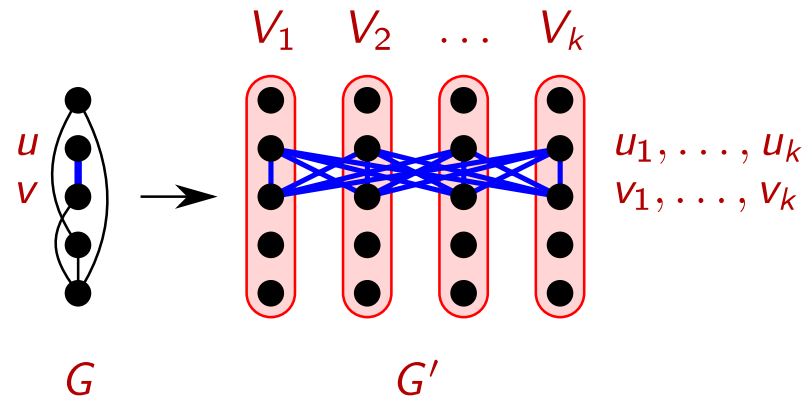
k -clique in $G \iff$ multicolored k -clique in G' .

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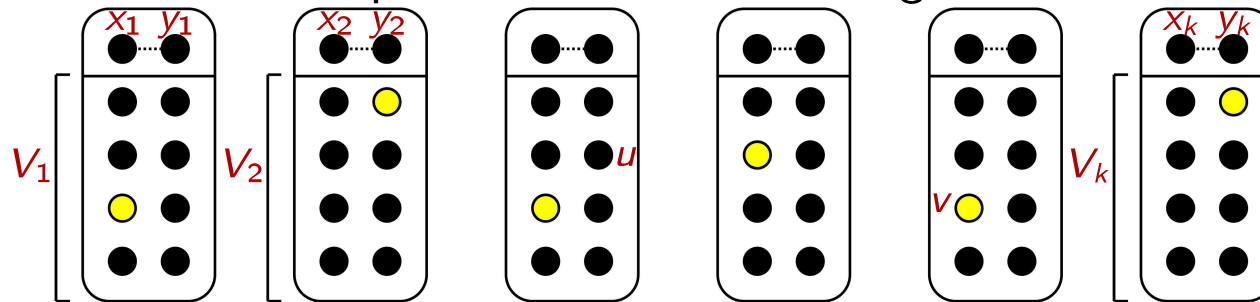
Similarly: reduction to **MULTICOLORED INDEPENDENT SET**.

DOMINATING SET

Theorem

There is a parameterized reduction from **MULTICOLORED INDEPENDENT SET** to **DOMINATING SET**.

Proof: Let G be a graph with color classes V_1, \dots, V_k . We construct a graph H such that G has a multicolored k -clique iff H has a dominating set of size k .



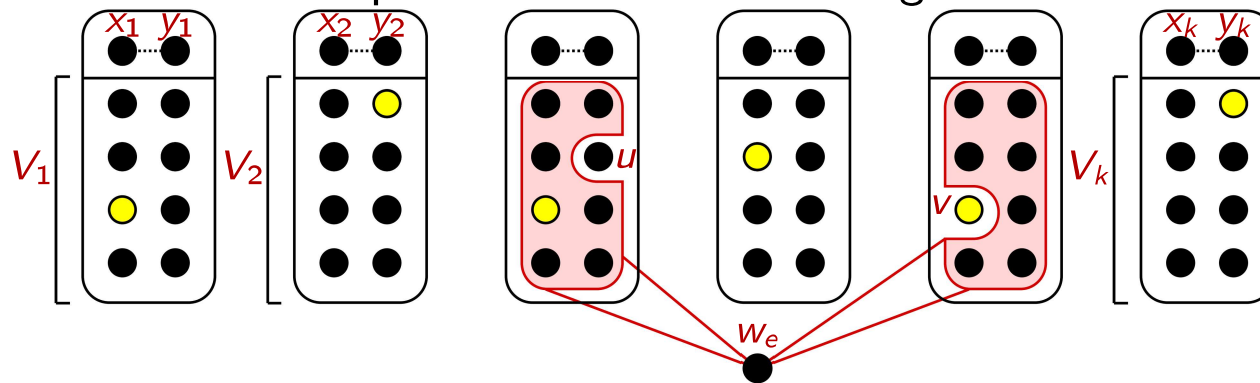
- The dominating set has to contain one vertex from each of the k cliques V_1, \dots, V_k to dominate every x_i and y_i .

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- The dominating set has to contain one vertex from each of the k cliques V_1, \dots, V_k to dominate every x_i and y_i .
- For every edge $e = uv$, an additional vertex w_e ensures that these selections describe an independent set.

Variants of DOMINATING SET

- **DOMINATING SET**: Given a graph, find k vertices that dominate every vertex.
- **RED-BLUE DOMINATING SET**: Given a bipartite graph, find k vertices on the red side that dominate the blue side.
- **SET COVER**: Given a set system, find k sets whose union covers the universe.
- **HITTING SET**: Given a set system, find k elements that intersect every set in the system.

All of these problems are equivalent under parameterized reductions, hence at least as hard as **CLIQUE**.

Basic hypotheses

It seems that parameterized complexity theory cannot be built on assuming $P \neq NP$ – we have to assume something stronger.

Engineers' Hypothesis

k -CLIQUE cannot be solved in time $f(k) \cdot n^{O(1)}$.

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k -STEP HALTING PROBLEM (is there a path of the given NTM that stops in k steps?) cannot be solved in time $f(k) \cdot n^{O(1)}$.

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Exponential Time Hypothesis (ETH)

n -variable 3SAT cannot be solved in time $2^{o(n)}$.

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Summary

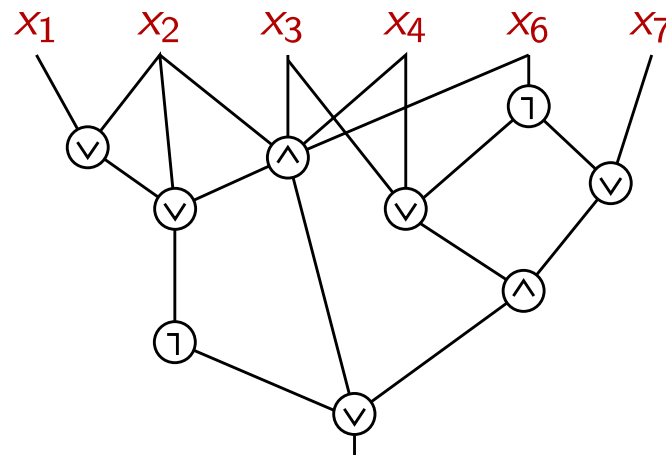
- INDEPENDENT SET and k -STEP HALTING PROBLEM can be reduced to each other \Rightarrow Engineers' Hypothesis and Theorists' Hypothesis are equivalent!
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Summary

- INDEPENDENT SET and k -STEP HALTING PROBLEM can be reduced to each other \Rightarrow Engineers' Hypothesis and Theorists' Hypothesis are equivalent!
- INDEPENDENT SET and k -STEP HALTING PROBLEM can be reduced to DOMINATING SET.
- Is there a parameterized reduction from DOMINATING SET to INDEPENDENT SET?
- Probably not. Unlike in NP-completeness, where most problems are equivalent, here we have a hierarchy of hard problems.
 - INDEPENDENT SET is $W[1]$ -complete.
 - DOMINATING SET is $W[2]$ -complete.
- Does not matter if we only care about whether a problem is FPT or not!

Boolean circuit

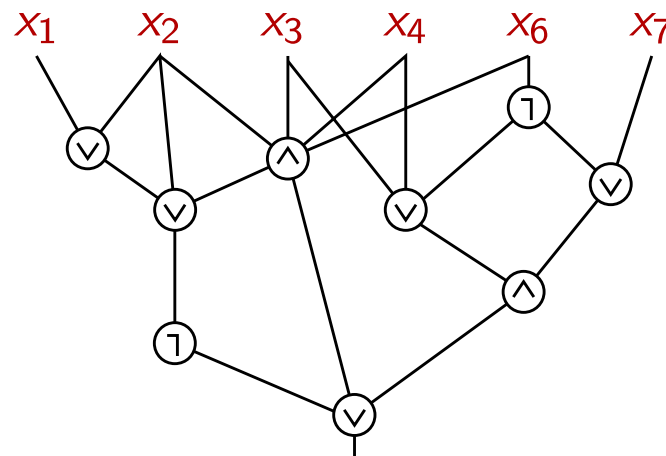
A **Boolean circuit** consists of input gates, negation gates, AND gates, OR gates, and a single output gate.



CIRCUIT SATISFIABILITY: Given a Boolean circuit C , decide if there is an assignment on the inputs of C making the output true.

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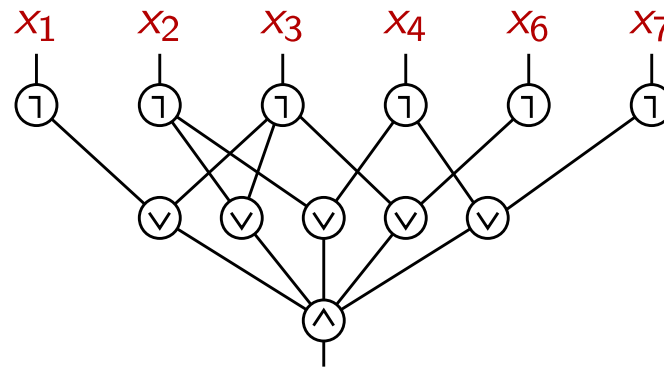
CIRCUIT SATISFIABILITY: Given a Boolean circuit C , decide if there is an assignment on the inputs of C making the output true.

Weight of an assignment: number of true values.

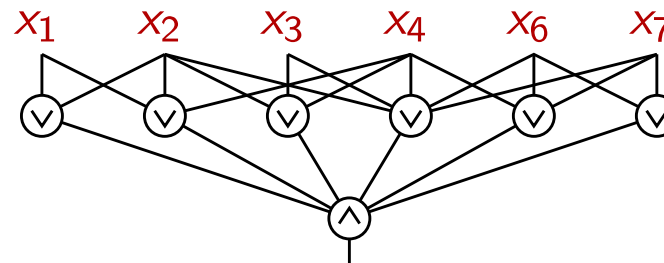
WEIGHTED CIRCUIT SATISFIABILITY: Given a Boolean circuit C and an integer k , decide if there is an assignment of weight k making the output true.

WEIGHTED CIRCUIT SATISFIABILITY

INDEPENDENT SET can be reduced to WEIGHTED CIRCUIT SATISFIABILITY:

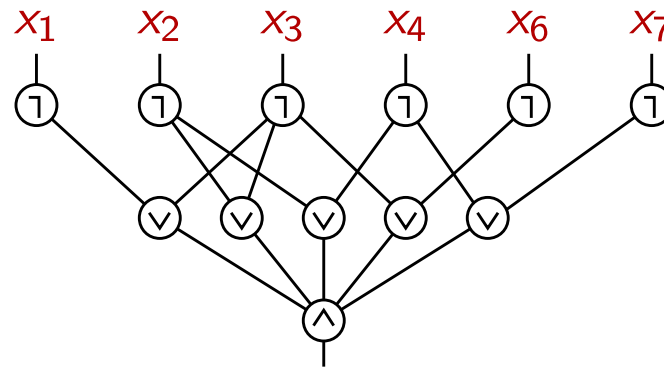


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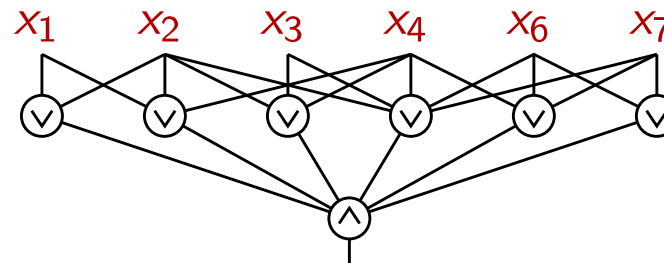


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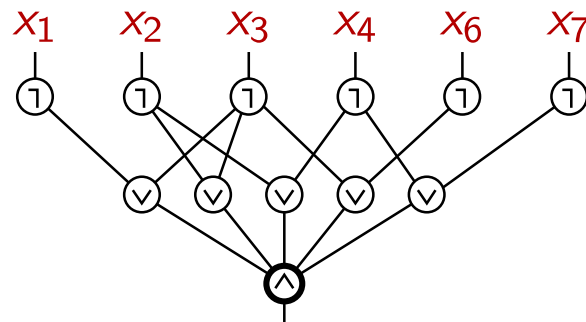


To express DOMINATING SET, we need more complicated circuits.

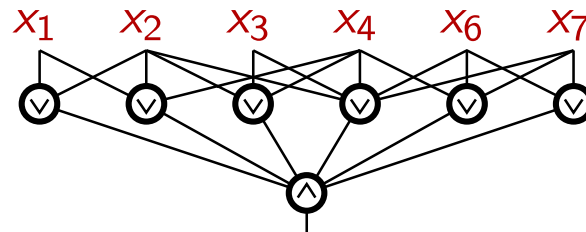
Depth and weft

The **depth** of a circuit is the maximum length of a path from an input to the output. A gate is **large** if it has more than 2 inputs. The **weft** of a circuit is the maximum number of large gates on a path from an input to the output.

INDEPENDENT SET: weft 1, depth 3



DOMINATING SET: weft 2, depth 2



The W-hierarchy

Let $C[t, d]$ be the set of all circuits having weft at most t and depth at most d .

Definition

A problem P is in the class $W[t]$ if there is a constant d and a parameterized reduction from P to **WEIGHTED CIRCUIT SATISFIABILITY** of $C[t, d]$.

We have seen that **INDEPENDENT SET** is in $W[1]$ and **DOMINATING SET** is in $W[2]$.

Fact: **INDEPENDENT SET** is $W[1]$ -complete.

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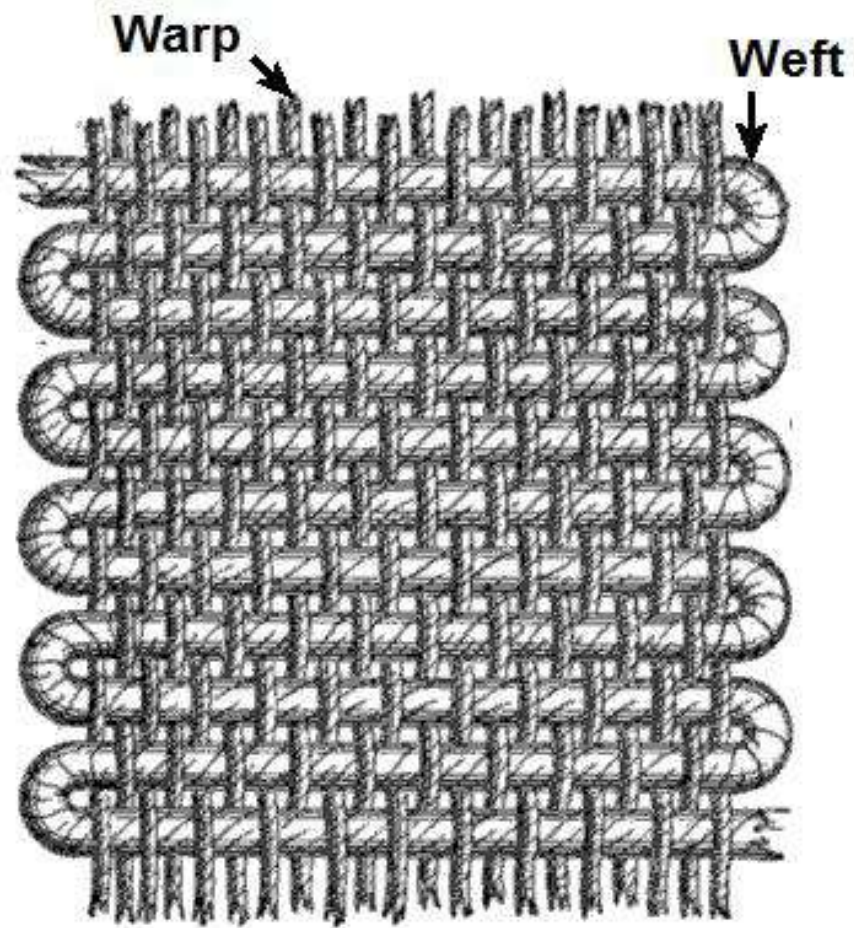
Fact: **DOMINATING SET** is $W[2]$ -complete.

If any $W[1]$ -complete problem is FPT, then $FPT = W[1]$ and every problem in $W[1]$ is FPT.

If any $W[2]$ -complete problem is in $W[1]$, then $W[1] = W[2]$.

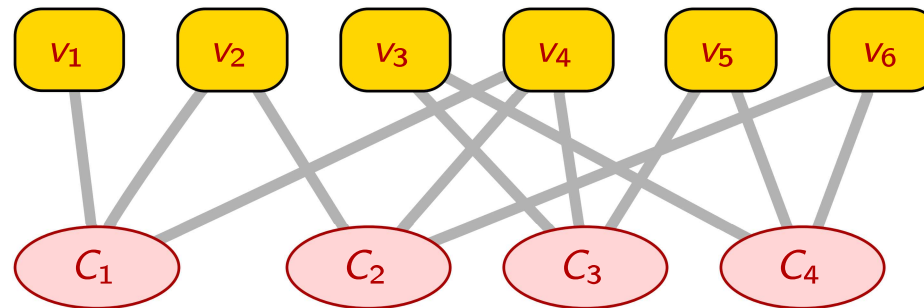
\Rightarrow If there is a parameterized reduction from **DOMINATING SET** to **INDEPENDENT SET**, then $W[1] = W[2]$.

Weft



Parameterized reductions

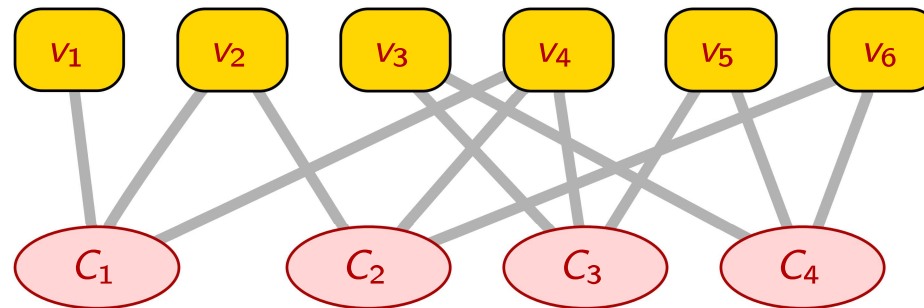
Typical **NP**-hardness proofs: reduction from e.g., **CLIQUE** or **3SAT**, representing each vertex/edge/variable/clause with a gadget.



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Types of parameterized reductions:

- Reductions keeping the structure of the graph.
 - **CLIQUE** \Rightarrow **INDEPENDENT SET**
- Reductions with vertex representations.
 - **MULTICOLORED INDEPENDENT SET** \Rightarrow **DOMINATING SET**
- Reductions with vertex and edge representations.

ODD SET

ODD SET: Given a set system \mathcal{F} over a universe U and an integer k , find a set S of at most k elements such that $|S \cap F|$ is odd for every $F \in \mathcal{F}$.

Theorem

ODD SET is $W[1]$ -hard parameterized by k .

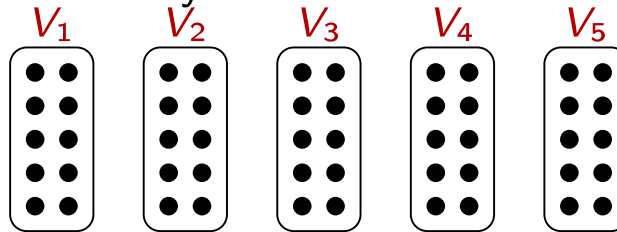
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First try: Reduction from MULTICOLORED INDEPENDENT SET. Let $U = V_1 \cup \dots \cup V_k$ and introduce each set V_i into \mathcal{F} .

\Rightarrow The solution has to contain exactly one element from each V_i .



If $xy \in E(G)$, how can we express that $x \in V_i$ and $y \in V_j$ cannot be selected simultaneously?

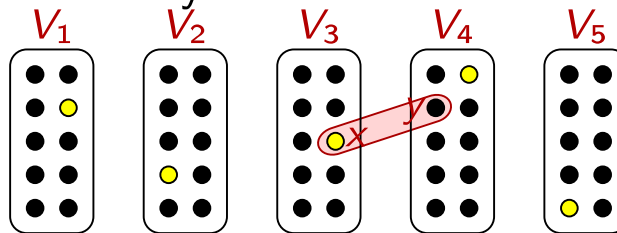
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- introducing $\{x, y\}$ into \mathcal{F} forces that **exactly one** of x and y appears in the solution,

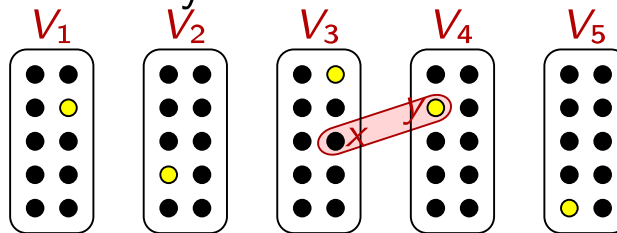
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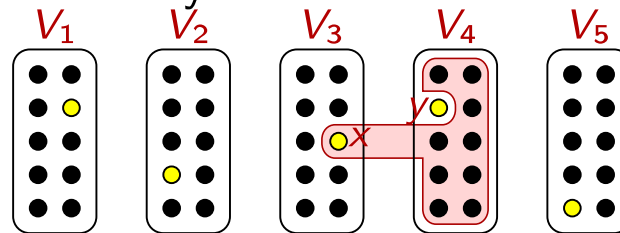
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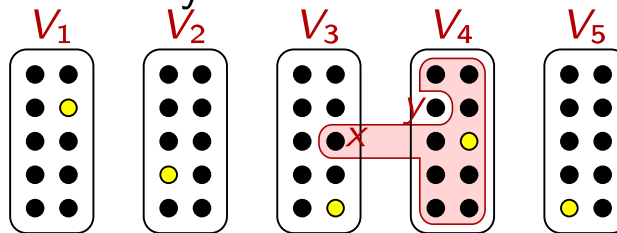
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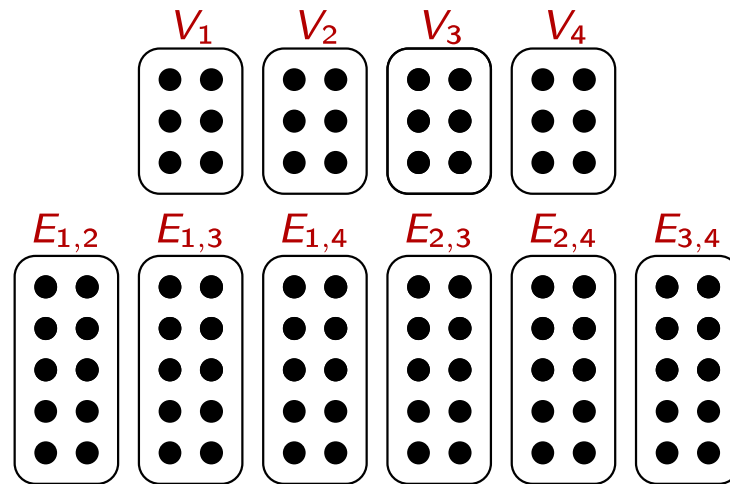
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Reduction from MULTICOLORED CLIQUE.

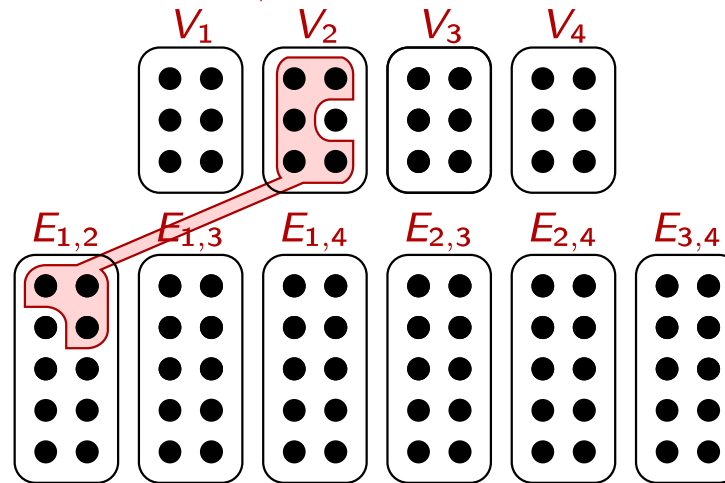
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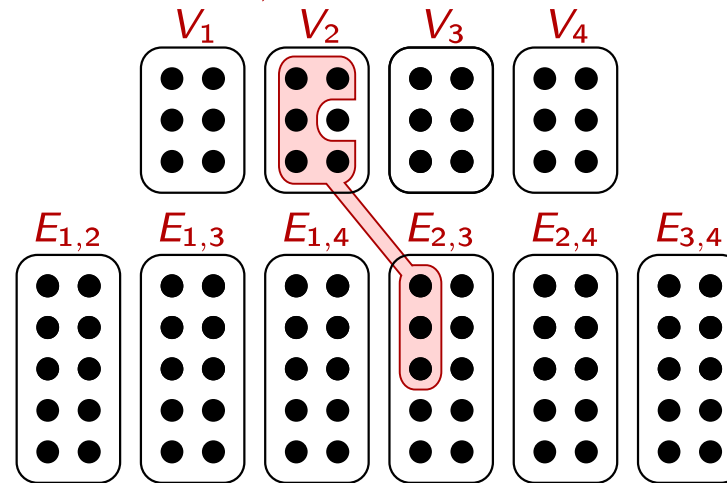
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- For every $v \in V_i$ and $x \neq i$, we introduce the sets:
 $(V_i \setminus \{v\}) \cup \{\text{every edge from } E_{i,x} \text{ with endpoint } v\}$
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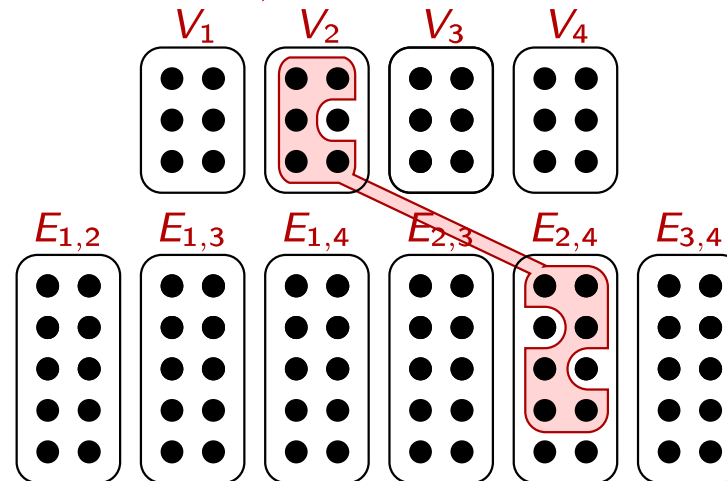
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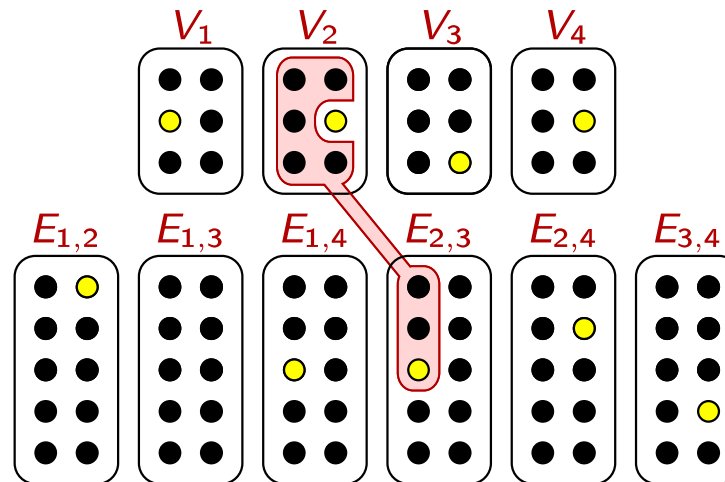
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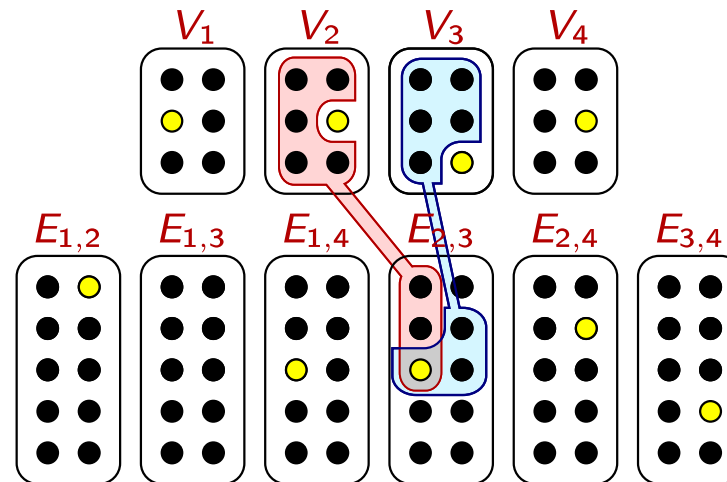
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- $v \in V_i$ selected \iff edges with endpoint v are selected from $E_{i,x}$ and $E_{x,i}$



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- For every $v \in V_i$ and $x \neq i$, we introduce the sets:
 $(V_i \setminus \{v\}) \cup \{\text{every edge from } E_{i,x} \text{ with endpoint } v\}$
 $(V_i \setminus \{v\}) \cup \{\text{every edge from } E_{x,i} \text{ with endpoint } v\}$
- $v \in V_i$ selected \iff edges with endpoint v are selected from $E_{i,x}$ and $E_{x,i}$
- $v_i \in V_i$ selected \iff edge $v_i v_j$ is selected in $E_{i,x}$
 $v_j \in V_j$ selected



Vertex and edge representation

Key idea

- Represent the vertices of the clique by k gadgets.
- Represent the edges of the clique by $\binom{k}{2}$ gadgets.
- Connect edge gadget $E_{i,j}$ to vertex gadgets V_i and V_j such that if $E_{i,j}$ represents the edge between $x \in V_i$ and $y \in V_j$, then it **forces** V_i to x and V_j to y .

Variants of HITTING SET

The following problems are $W[1]$ -hard, with very similar proofs:

- ODD SET
- EXACT ODD SET (find a set of size exactly k ...)
- EXACT EVEN SET
- UNIQUE HITTING SET
(at most k elements that hit each set exactly once)
- EXACT UNIQUE HITTING SET
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A problem that is also $W[1]$ -hard, but requires very different techniques:

- EVEN SET: Given a set system \mathcal{F} and an integer k , find a **nonempty** set S of at most k elements such $|F \cap S|$ is even for every $F \in \mathcal{F}$.

Summary

- By parameterized reductions, we can show that lots of parameterized problems are at least as hard as **CLIQUE**, hence unlikely to be fixed-parameter tractable.
- Connection with Turing machines gives some supporting evidence for hardness (only of theoretical interest).
- The **W**-hierarchy classifies the problems according to hardness (only of theoretical interest).
- Important trick in **W[1]**-hardness proofs: vertex and edge representations.